

Execution Generated Test Cases: How to Make Systems Code Crash Itself

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Abstract

This paper presents a technique that uses code to automatically generate its own test cases at run-time by using a combination of symbolic and concrete (i.e., regular) execution. The input values to a program (or software component) provide the standard interface of any testing framework with the program it is testing, and generating input values that will explore all the “interesting” behavior in the tested program remains an important open problem in software testing research. Our approach works by turning the problem on its head: we lazily generate, from within the program itself, the input values to the program (and values derived from input values) as needed. We applied the technique to real code and found numerous corner-case errors ranging from simple memory overflows and infinite loops to subtle issues in the interpretation of language standards.

1 Introduction

Systems code is difficult to test comprehensively. Externally, systems interfaces tend towards the baroque, with many different possible behaviors based on tricky combinations of inputs. Internally, their implementations tend towards heavily entangling nests of conditionals that are difficult to enumerate, much less exhaust with test cases. Both features conspire to make comprehensive, manual testing an enormous undertaking, so enormous that empirically, many systems code test suites consist only of a handful of simple cases or, perhaps even more commonly, none at all.

Random testing can augment manual testing to some degree. A good example is the fuzz [22, 21] tool, which automatically generates random inputs, which is enough to find errors in many applications. Random testing has

the charm that it requires no manual work, other than interfacing the generator to the tested code. However, random test generation by itself has several severe drawbacks. First, blind generation of values means that it misses errors triggered by narrow ranges of inputs. A trivial example: if a function only has an error if its 32-bit integer argument is equal to “12345678” then random will most likely have to generate billions of test cases before it hits this specific case. Second, and similarly, random testing has difficulty hitting errors that depend on several different inputs being within specific (even wide) ranges of values. Third, the ability of random testing to effectively generate random noise is also its curse. It is very poor at generating input that has structure, and as a result will miss errors that require some amount of correct structure in input before they can be hit. A clear example would be using random test generation to find bugs in a language parser. It will find cases where the parser cannot handle garbage inputs. However, because of the extreme improbability of random generation constructing inputs that look anything like legal programs it will miss almost all errors cases where the parser mis-handles them.

Of course, random can be augmented with some amount of guidance to more intelligently generate inputs, though this comes at the cost of manual intervention. A typical example would be writing a tool to take a manually-written language grammar and use it to randomly generate legal and illegal programs that are fed to the tested program. Another would be having a specification or model of what a function’s external behavior is and generate test cases using this model to try to hit “interesting” combinations. However, all such hybrid approaches require manual labor and, more importantly, a willingness of implementors to provide this labor at all. The reluctance of systems builders to write specifications, grammars, models of what their code does, or even assertions is well known. As a result, very few real systems have used such approaches.

*This exact text (with author names elided) was submitted to the 20th ACM Symposium on Operating Systems Principles, March 25, 2005.

This paper’s first contribution is the observation that code can be used to *automatically* generate its own potentially highly complex test cases. At a high level, the basic idea is simple. Rather than running the code on manually-constructed concrete input, we instead run it on symbolic input that is initially allowed to be “anything.” As the code observes this input, these observations tell us what legal values (or ranges of values) the input could be. Each time the code makes a decision based on an observation we conceptually fork the execution, on one branch we add the constraint that the input satisfies the observation, on the other that it does not. We can then generate test cases by solving these constraints for concrete values. We call such tests *execution generated testing* (EGT).

This process is most easily seen by example. Consider the following contrived routine `bad_abs` that incorrectly implements absolute value:

```

0:  int bad_abs(int x) {
1:      if(x < 0)
2:          return -x;
3:      if(x == 12345678)
4:          return -x;
5:      return x;
6:  }
```

As mentioned before, even such a simple error will probably take billions of random-generated test cases to hit. In contrast, finding it with execution generated testing it is straightforward. Symbolic execution would proceed as follows:

1. Initial state: set x to the symbolic value of “anything.” In this case, before any observations at all, it can be any value between `INT_MIN` and `INT_MAX`. Thus we have the constraints $x \geq INT_MIN \wedge x \leq INT_MAX$.
2. Begin running the code.
3. At the first conditional (line 1) fork the execution, setting x to the symbolic constraint $x < 0$ on the true path, and to $x \geq 0$ on the false path.
4. At the return on (line 2) solve the constraints on x for a concrete value (such as $x == -1$). This value is later used as a test input to `bad_abs`.
5. At the second conditional (line 3) fork the execution, setting x to the constraints $x \equiv 12345678 \wedge x \geq 0$ on the true path and $x \neq 12345678 \wedge x \geq 0$ on the false path.
6. At the return on line 4 solve the symbolic constraints $x \equiv 12345678 \wedge x \geq 0$. The value is 12345678 is our second test case.

7. Finally, at line 5, solve x ’s constraints for a concrete value (e.g., $x = 1$). This value is used as our third, final case.

We can then test the code on the three generated values for x . Of course, this sketch leaves many open questions — when to generate concrete values, how to handle system calls, how to tell what is correct, etc. The rest of the paper discusses these issues in more detail.

There are a couple of ways to look at the approach. From one point of view, implementation code has a “grammar” of the legal inputs it accepts and acts on, or rejects. EGT is an automatic method to extract this grammar (and the concrete sentences it accepts and rejects) from the implementation rather than from a hand-written specification. From another viewpoint, it can be seen as a way to turn code “inside out” so that instead of consuming inputs becomes a generator of them. Finally, and perhaps only half-vacuously, it can be viewed as a crude analogue of the Heisenberg effect in the sense that unlike observations perturbing experiments from a set of potential states into a variety of concrete ones, observations in this case perturb a set of possible inputs into a set of increasingly concrete ones. The more precise the observation the more definitively it perturbs the input. The most precise observation, an equality comparison, fixes the input to a specific concrete value. The least precise, an inequality, simply disallows a single value but leaves all others as possibilities.

This paper has three main contributions:

1. A simple conceptual approach to automatically generate test cases by running code on symbolic inputs.
2. A working prototype EGT system.
3. Experimental results showing that the approach is effective on real code.

The paper is organized as follows. Section 2 gives an overview of the method. Section 3 discusses concrete implementation issues. The next four sections give four case studies of applying the approach to systems code. Finally, Section 7 discusses related work and Section 8 concludes.

2 Overview

This section gives an overview of EGT. The next section discusses some of the implementation details.

In order to generate test cases, EGT runs the code on symbolic rather than real input. Whenever code reads from its environment (via network packets, command line options, files, etc) we want to instead return a symbolic variable that has no constraints on its actual value. As the program executes and uses or observes this value

(e.g., through comparisons), we add constraints based on these observations. Then, to determine how to reach a given program path, we solve these constraints and generate input that satisfies them.

At a high-level, the EGT system has three core activities:

1. Instrumentation to track symbolic constraints. Our prototype EGT system instruments the tested code using a source-to-source transformation. This instrumentation inserts checks around every assignment, expression and branch in the tested program and calls into our runtime system. It also inserts code to fork a new process at each decision point at which the associated boolean condition could return both `true` and `false`.
2. Constraint solving: We model our constraints using formulas of quantifier-free first-order logics as represented by CVCL, a state-of-the-art decision procedure solver [4, 15]. CVCL has been used in applications ranging hardware verification to program analysis to mathematical theorem proving.

We use CVCL in two ways. First, after every branch point we call it to determine if the current set of constraints is satisfiable. If not, we stop following the code path, otherwise we continue. CVCL is sound: if it states that a no solution exists, it is correct. Second, at the end of a code path that uses symbolic input, we use CVCL to generate concrete values to use as test input.

3. Modeling. External functions that return or consume input can either be modeled so that they work with symbolic variables, or not modeled, in which case any value they take must be made concrete. In general, one can leave most things unmodeled, with the downside that testing coverage will be reduced. Models are not that hard to write. A four-line model for the Unix `recv` system call is given in Section 6. In addition, models can be used to speed up the test generation. This optimization is discussed in Section 3.4.

The mechanical act of instrumenting code is pretty easy, and there are a lot of constraint solvers to pick from and use as black boxes. Thus, the main challenge for the approach is how to run code symbolically. The next subsection talks about this in more detail.

2.1 The basic idea for symbolic execution

The basic idea behind our approach is that when we perform logical or arithmetic operations, we generate constraints for these, and when we perform control flow decisions, we fork execution and go down both paths. This

section sketches how we can symbolically execute code. For ease of exposition, we initially assume that all the variables in a program are symbolic; Section 3.2 shows how we can intermix symbolic and concrete execution in order to efficiently process real code.

Assignment: $v = e$. We symbolically do an assignment of an expression e to a variable v by generating the constraint that $v \equiv e$. For example, $v = x + y$ generates the constraint that $v \equiv x + y$; other arithmetic and logical operators are similar.

The complication is that v may have been involved in previous constraints. We must distinguish the newly assigned value of v from its use in any already generated constraints. For example, assume we have two assignments: (1) $x = y$ and then (2) $y = 3$. The first assignment will generate the constraint that $x \equiv y$. The second will generate the constraint $y \equiv 3$. At this point, the constraints imply $x \equiv 3$, which is obviously nonsensical. This new value for y after its assignment $y = 3$ has nothing to do with any prior constraints involving y and should have no impact on them. Thus, an assignment $v = e$ must have two parts. First, generate a new location for v and only then generate the constraint that $v \equiv y$.¹

If-statements. We symbolically execute an if-statement as follows: (1) fork execution at the conditional, (2) on the true path add the constraint that the conditional expression e is true ($e \equiv \text{true}$) and continue, (3) on the false path add the constraint that e is false ($e \equiv \text{false}$) and continue. For example:

concrete		symbolic
if (e)		if ($\text{fork}() == \text{child}$)
s1;		add_constraint($e == \text{true}$);
		s1;
else		else
s2;		add_constraint($e == \text{false}$);
		s2;

Loops. We transform loops into if-statements with `goto`'s so they are handled as above. One danger is that iterating on a symbolic loop variable can continue forever, forking a new execution on each evaluation of the loop condition. The usual practical hack is to only iterate a fixed number of times or for a fixed amount of time (we do the latter). Neither solution is perfect. However, in our context almost any solution is preferable to manual test generation.

Function calls: $f(x)$. There are three differences between a symbolic function call and an imperative, call-by-value call. First, control can return multiple times into the caller, once for each fork-branching that occurs. Second, constraints placed on x in the body of f must prop-

¹ Alternatively, ignoring aliasing, we could have equivalently gone through all existing constraints involving v and relabeled them to use a new, fresh name.

```

// initial constraints:
//      x >= INT_MIN \wedge x <= INT_MAX
int symbolic_bad_abs(int x) {
    // holds the return expression.
    ret = new symbol;

    // fork execution at each branch point.
    if(fork() == child)
        add_constraint(x < 0);
        add_constraint(ret = -x);

        // first return, final constraints:
        //      x >= INT_MIN \wedge x <= INT_MAX
        //      \wedge x < 0 \wedge ret = -x
        return ret;
    else
        add_constraint(x >= 0);

    // fork execution
    if(fork() == child)
        add_constraint(x = 12345678);
        add_constraint(ret = -x);

        // second return, final constraints:
        //      x >= INT_MIN \wedge x <= INT_MAX
        //      \wedge x >= 0
        //      \wedge x = 12345678 \wedge ret = -x
        return ret;
    else
        add_constraint(x != 12345678);

        add_constraint(ret = x);
        // last return final constraints:
        //      x >= INT_MIN \wedge x <= INT_MAX
        //      \wedge x >= 0
        //      \wedge x != 12345678 \wedge ret = x
        return ret;
}

```

Figure 1: A symbolic translation of `bad_abs`.

agate up to the caller. For example, the concrete code:

```

int foo(int x) {
    if(x == 3)
        return 1;
    else
        return 2;
}

```

will generate a symbolic execution that returns twice into the caller, since the branch will cause a forked execution. On the true branch we want to propagate the constraint that $x \equiv 3$ back to the caller and on the false that $x \neq 3$. The final difference is that at the exit point from a function, we create a temporary symbolic variable and return that as the function’s expression value.

Figure 1 gives a symbolic translation of `bad_abs`

based on the above rules.

2.2 What is correctness?

EGT, like all testing approaches, needs to have some notion of what “bad” behavior is so that it can flag it. We use three approaches to do so.

First, and unsurprisingly, check for program independent properties, such as segmentation faults, storage leaks, memory overflows, division by zero, deadlocks, uses of freed memory, etc.

Second, do cross-checking. If a piece of code implements an important interface, then there are likely to be several implementations of it. These implementations can be cross-checked against each other by running the test cases generated from one implementation (or both) on both implementations and flagging differences. One important usage model: after modifying a new version of a system, cross-check it against the old version to make sure any change was intended. This approach works especially well for complex interfaces.

Third, specification-by-example. While writing specifications to state what exactly code must do in general is hard, it is often much easier to take the specific test cases our tool generates and specify what the right answers are just for these cases. For example, for the `bad_abs` routine, the EGT system generates the three concrete values: $-3, 12345677, 12345678$. Thus, for testing we would just do:

```

assert(bad_abs(-3) == 3);
assert(bad_abs(12345677) == 12345677);
assert(bad_abs(12345678) == 12345678);

```

3 Implementation Issues

This section discusses some of EGT’s implementation aspects more concretely.

3.1 Transformations to the input CFG

We use the CIL tool [24], designed for writing program analyses and source-to-source transformations of C programs to instrument the code of tested programs. The main benefit of using CIL is that it compiles C to a high-level representation that is then “lowered” to a representation that has fewer constructs than C, reducing the number of cases we would have to handle in a stock compiler.

In addition to CIL’s default lowering, we did several simplifying transformations of our own. Both CIL’s and our transformations occur before we do any instrumentation (described in the next subsection).

First, all higher-level constructs such as `while` loops, `for` loops and `switch` statements are translated so that

all variables in the program appear only in assignments and `if` branches. Once this is accomplished, we start transforming each assignment and branch in the modified program. Assignments are reduced to one of two general forms: function calls, and assignments which contain only variables and primitive operators (a single binary or unary operator) on the right hand side.

For example, the following assignment:

```
int a = max_abs(max_abs(b, c), d) + e;
```

is broken down to the following three assignments:

```
int tmp1 = max_abs(b, c);
int tmp2 = max_abs(tmp1, d);
int a = tmp2 + e;
```

The C transformer also rewrites each `if` clause to contain only simple conditions, that is conditions with no logical and or logical `or`. The `?` operator is also rewritten as an `if` clause.

After these transformations, the program representation is then fed to our instrumentation code. We sketch the rewrite rules in the next subsection along with some of the practical details.

3.2 Mixed symbolic and concrete execution

Ignoring memory and solver-limitations, we can run any code entirely symbolically until it interacts with the outside, concrete world. For example, if it calls external code, or sends a packet on a real network to a machine running concrete code, or prints output to be read by a real person. At this point you must either make the inputs to the external code concrete (e.g., you must send data rather than a symbolic constraint in a network packet), or, alternatively, make a model of the world to pull it into the simulation.

In practice, constraint solvers are not as robust as one might hope and so without care overzealous constraint generation will blow them up, sometimes for good theoretic reasons, sometimes for unimpressive practical ones. Further, symbolic-only execution is expensive in both speed and space. Thus, we do a hybrid approach that intermixes concrete and symbolic execution. The basic approach is that before every operation we dynamically check if the values are all concrete. If so, we do the operation concretely. Otherwise, if at least one value is symbolic we do the operation symbolically (using the logic described in Section 2.1).

We sketch how to conceptually rewrite source constructs for a C-like language so that they can run on either concrete or symbolic values, mentioning some of the more important practical details.

Our first transformation conceptually changes each variable or expression `v` to have two instances: a concrete one (denoted `v.concrete`) and a symbolic one (denoted `v.symbolic`). If `v` is con-

```
assign_rule(T &v, T e) {
    if(e is concrete)
        // equivalent to v.concrete = e.concrete;
        // v.symbolic = <invalid>;
        v = (concrete=e.concrete, symbolic=<invalid>);
    else
        // equivalent: v.symbolic = e.symbolic
        v = (concrete=<invalid>, symbolic=new symbolic var T);
        constraint(v.symbolic = e.symbolic);
}
```

Figure 2: Rewrite rule for assignment `v = e` for any variable `v` and expression `e` of type `T`.

crete, `v.concrete` holds its concrete value and `v.symbolic` contains the special token `<invalid>`. Conversely, if `v` is symbolic, `v.symbolic` holds its symbolic value and `v.concrete` is set to `<invalid>`.

In practice, we track the `v.symbolic` field using a table lookup that takes the address of a the variable `v` (which gives it a unique name) and returns `v`'s associated “shadow” symbolic variable `v.symbolic` (if it is symbolic) or null (if it is concrete). In the latter case, the variable `v` contains the concrete value (`v.concrete`) and can just be used directly. The following examples assume explicit concrete and symbolic fields for clarity.

The most basic operation is assignment. Figure 2 gives the basic assignment rule. If the right hand variable `e` is a concrete expression or variable, just assign its concrete value to the left-hand side `v` and mark `v`'s symbolic component as `invalid`. If `e` is symbolic, then as explained in the previous section, we must allocate a fresh symbolic variable to be used in any new constraints that are generated. After that, we first set `v.concrete` to be `invalid` and then add the constraint that `v.symbolic` equals `e.symbolic`.

It may not be immediately obvious but the same effect could have been achieved by simple assignment, since two symbolic variables constrained to be equal can just be the same variable. E.g.,

```
v = (concrete=<invalid>, symbolic=e.symbolic);
```

or even

```
v = e;
```

since `e` already has its concrete component set to `invalid`.

Roughly as simple are basic binary arithmetic operators. Figure 3 gives the rewrite rule for binary addition; other binary arithmetic operators are similar. If both `x` and `y` are concrete, we just return an expression whose concrete part is just their addition and symbolic part is `invalid`. Otherwise we build a symbolic constraint `s` and then return an expression that has `s` as its symbolic component and `invalid` for its concrete.

The rewrite rule for `if`-statements is a straight-forward

```

// rule for x + y
T plus_rule(T x, T y) {
  if(x and y are concrete)
    return (concrete=x.concrete + y.concrete, <invalid>);

  s = new symbolic var T;
  if(x is concrete)
    constraint(s = x.concrete + y.symbolic);
  else if y is concrete
    constraint(s = x.symbolic + y.concrete);
  else
    constraint(s = x.symbolic + y.symbolic);
  return (concrete=<invalid>, symbolic=s);
}

```

Figure 3: Rewrite rule for “ $x + y$ ” where variables x and y are of type T .

```

// rule for *p
T deref_rule(T* p) {
  if(*p is concrete)
    return (concrete=*p, symbolic=<invalid>);
  else
    s = new symbolic var T;
    if(p is concrete)
      constraint(s = (*p).symbolic);
    else
      // symbolic dereference of p
      constraint(s = deref(p.symbolic));
    return (concrete=<invalid>, symbolic=s);
}

```

Figure 4: Rewrite rule for dereference “ $*p$ ” of any pointer p of type T . The main complication occurs when we dereference a symbolic pointer: in this case we must add a symbolic constraint on the dereferenced value.

combination of the purely symbolic rule for if-statements with the similar type of concrete-symbolic checking that occurs in binary relations. There are two practical issues. First, our current system will happily loop on symbolic values — the parent process of a child doing such looping will terminate it after a timeout period expires. Second, we use the Unix `fork` system call to clone the execution at every symbolic branch point. Naively this will quickly lead to an exponential number of processes executing. Instead we have the parent process wait for the child to finish before continuing to execute on its branch of the conditional. This means we essentially do depth-first search where there will only be one active process and a chain of its predecessors who are sleeping waiting for the active process to complete.

Because dereference deals with storage locations, it is one of the least intuitive rewrite rules. Figure 4 gives the rewrite rule for dereferencing $*p$. A concrete dereference works as expected. A dereference of a concrete

pointer p that points to a symbolic value also works as expected (i.e., just like assignment, except that the rvalue is dereferenced). However, if p itself is symbolic, then we cannot actually dereference it to get what it points to but instead must generate a funny constraint that says that the result of doing so equals the symbolic dereference of p .

At an implementation level, CVCL currently does not handle symbolic dereferences so we do not either. Further, in the short term we do not really do the right thing with any pointer dereference that involves a symbolic value (such as a symbolic offset off of a concrete pointer or a symbolic index into a symbolic array). In such cases we will generate a concrete value, which may be illegal.

One happy result of this limitation is that, when combined with the the way the implementation uses a lookup table to map variables to their shadow symbolic values, it makes handling address-of trivial. For example, given the assignment $p = \&v$ we simply do the assignment, always, no matter if v is a symbolic or concrete. A lookup of p will return the same symbolic variable (if any) that lookup of $\&v$ does. Thus any constraints on it are implicitly shared by both. Alternatively, if there is no symbolic, then p will point directly at the concrete variable and dereference will work as we want with no help.

Conceptually, function calls are rewritten similarly to the previous section. The implementation is slightly more messy since we essentially rewrite the signature to add an additional parameter for each original parameter and use this to pass the symbolic variable associated with each parameter (or null if there is none). For example:

concrete	rewritten
void f(T x) {	void f(T x, T *x_symbolic) {
	bind(&x, x_symbolic);
...	...
}	}

And the caller becomes:

f(x, lookup(x));

3.3 Constraint solving issues

CVCL has two engines. An “integer” engine that works well with integer arithmetic, including the non-linear operations multiplication and division, but does not handle modulo or bitwise operations (and, or, xor). The other is a “bitvector” engine that works well with bitwise logical operations and arithmetic except for modulo and division. Additionally, they have a variety of exponential and doubly-exponential algorithms buried inside, which means that they differ dramatically and unpredictably in terms of solution time and ability to generate concrete values from constraints.

Thus, we represent all constraints in our own solver-

independent form which is translated to a solver-dependent form only when communicating to the solver. This lets us translate between either engine or, in the future, to an entirely different solver.

Additionally, to isolate the effects of the constraint solver we run it in its own child Unix process so that (1) we can kill it if it does not terminate and (2) any problems it runs into in terms of memory or exceptions are isolated.

3.4 Creating a model for speed

Not all the code in the program under testing should be given the same level of attention. For example, many of our benchmarks make intensive use of the string library, but we don't want to generate test cases that exercise the code in these string routines.

More precisely, imagine a program which uses `strcmp` to compare two of its symbolic strings. Most implementations of `strcmp` would traverse one of the strings, and would compare each character in the first string with the corresponding character in the second string and would return a value when the two characters differ or when the end of a string has been reached. Thus, the routine would return to the caller approximately $2n$ times, each time with a different set of constraints. However, most applications use a routine such as `strcmp` as a black box, which could return only one of the following three values: 0, when the strings are equal, -1 when the first string is lexicographically smaller than the second one, and 1 otherwise. Returning the same value multiple times does not make any difference for the caller of the black box.

Instead of instrumenting routines such as those in the string library, we could instead provide models for them. A model for `strcmp` would return three times, once for each possible return value. After each fork, the model would add a series of constraints which would make the outcome of that branch symbolically true: for example, on the branch which returns 0, the model would add constraints setting the two strings equal. Of course, certain branches may be invalid; e.g. if the two strings have different lengths, `strcmp` could not return 0. In this case, the corresponding branch is simply terminated.

We implemented models for the routines in the string library, and used them in generating tests for our benchmarks. Adding these specifications has two main benefits. On the one hand, it removes useless test cases from the generated test suites (by removing tests which would only improve code coverage in the string routines), and on the other hand it significantly improves performance. For the WsMp3 benchmark that we evaluate in Section 6, the test suites are generated approximately seven times faster.

3.5 Discussion

Currently we do lazy evaluation of constraints, deferring solving them until the last possible moment. We could instead of eager evaluation, where as soon as we use a symbolic value we make up a concrete one. This eliminates the need to execute code symbolically. However, committing to a concrete value immediately precludes the ability to pick a different concrete value later, which will often be necessary to execute both paths of any subsequent branch based on the variable's value (since the concrete value will either satisfy the true or false branches, but not both). For example assume `x` is symbolic in the following code:

```
// assume x is symbolic
y = x; // make up concrete value for x (e.g., 4)
...
if(x == 4)
    foo();
else
    bar();
```

When we assign `x` to `y` we would have to make up a concrete. Assume we set `x` equal to 4. Then, we will not be able to execute the following false branch of the conditional. And, of course, we will not hit the true branch. To handle this problem we would have to checkpoint execution at each point where we made a value concrete and, if this decision precluded subsequent code paths, roll back, changing the concrete value and go back forward. A hybrid approach might be best, where we make up concrete values immediately and then only do full symbolic execution on code paths that this misses.

4 Micro-case study: Mutt's UTF8 routine

As the first micro-benchmark to evaluate EGT, we applied it to a routine used by the popular Mutt email client to convert strings from the UTF-8 to the UTF-7 format. As reported by Securiteam, this routine in Mutt versions up to version 1.4 have a buffer overflow vulnerability which may allow a malicious IMAP server to execute arbitrary commands on the client machine [23].

We selected this paper in part because it has been one of the examples in a recent reliability paper [25], which used a carefully hand-crafted input to exploit it.

We extracted the UTF8 to UTF7 conversion routine from Mutt version 1.4, ran the code through our tool, and generated test cases for different lengths of the UTF-8 input string. Running these generated tests immediately found the error.

The paper we took the code from suggested a fix of increasing the memory allocation ratio from $n*2$ to $n*7/3$. We applied this change to the code, and reran

the EGT generated test cases, which immediately flagged that the code still has an overflow. The fact that the adjusted ratio was still incorrect highlights the need for (and lack of) automated, comprehensive testing.

Table 1 presents our results. For each input size, we report the size of the generated test suite and the time it took to generate it, the cumulative statement coverage achieved up to and including that test suite, and the largest output size that we generated for that input size. These results (and all our later results), were generated on a Intel Pentium 4 Mobile CPU at 1.60GHz, with 512MB RAM.

Input Size	Generation Time	Test Suite Size	Statement Coverage	Largest Output
1	16s	10	84.0%	5
2	1m35s	38	94.2%	8
3	7m26s	132	94.2%	11
4	34m12s	458	95.6%	15
5	2h35m	1569	95.6%	19

Table 1: Test suites generated for utf8_to_utf7

5 Case study: printf

This section applies EGT to three different `printf` implementations. The `printf` routine is a good example of real systems code: a highly complex, tricky interface that necessitates an implementation with thickets of corner cases. Its main source of complexity is the output format string it takes as its first argument. The semantics of this single string absorb the bulk of the 234 lines the ANSI C99 standard devotes to defining `printf`; these semantics define an exceptionally ugly and startling programming language (which even manages to include iteration!).

Thus, `printf` is a best-case scenario for EGT. The standard and code complexity create many opportunities for bugs. Yet the inputs to test this complexity can be readily derived from `printf`'s parsing code, which devolves to fairly simple, easily solved equality checks. Further, the importance of `printf` means there are many different implementations, which we can use to finesse the need for a specification by cross-checking against each other.

We checked the following three `printf` implementations; all of them (intentionally) implemented only a subset of the ANSI C90 standard:

1. The Pintos instructional operating systems `printf`; the implementation intentionally elides floating point. This implementation is a stern test of EGT, since the developer (the co-author of a

```

" %11e" " %#0f" " %G%." " % +1"
" %#he" " %00." " %+jf" " %+"
" %-lf" " %#hf" " %+f" " %#.E"
" %00" " %.c" " %#i" " %s%o"
" % #c" " %-#. " " %c%' " " %c%j"
" %# p" " %---" " %1G" " %+-u"
" %'0" " %u" " %p%" " %9d"
" %+0" " %-9s" " %-0o" " %1lc"
" %0g" " %#+-" " %0 u" " %9s%"

```

Figure 5: A representative subset of the format strings EGT generated from the Pintos implementation.

widely-read C book) had intimate knowledge of the standard.

2. The `gccfast printf`, which implements a version of `printf` in terms of `fprintf`.²
3. A reduced-functionality `printf` implementation for embedded devices.³

We used EGT to generate test suites by making the format string the single symbolic argument to `printf`. We set the size of this symbolic string to a fixed length and generated test cases from the resultant constraints. We describe our measurements below and then discuss the bugs and differences found.

Measurements. We generated test cases for format strings of length 2, 3, 4, and 128. Table 2 shows the test suite size that we generated for each format length and the time it took to generate the test suite. We allowed a maximum of 30 seconds per CVCL query; there were only two queries killed after spending more than 30 seconds. For format lengths of 128 long, we terminated the test generation after approximately two hours.

Figure 5 gives a representative set of format strings of length 4. Note that while almost all look fairly bizarre, because they are synthesized from actual comparisons in the code, many are legal (and at some level “expected” by the code).

Results. After generating test suites, we checked the output for each `printf` in two ways. First, we took the tests each implementation generated and cross-checked its output on these tests against the output of glibc's `printf`. Each of the three implementations attempts to implement a subset of the ANSI C99 standard, while glibc intends to fully implement it. Thus, any difference is a potential bug. EGT discovered lots of such differences automatically: 426 in Pintos, 146 in the Embedded `printf` and 7 in GCCfast's `printf` (which

²<http://www.opensource.apple.com/darwinsource/WWDC2004/gccfast-1614/>

³<http://www.menie.org/georges/embedded/index.html>

```

/* Performs an integer conversion, writing
   output to OUTPUT with auxiliary data AUX.
   The integer converted has absolute value
   VALUE. If NEGATIVE is true the value is
   negative, otherwise positive. The output
   will use the given DIGITS, with strlen(DIGITS)
   indicating the output base. Details of the
   conversion are in C. */

static void
format_integer (uintmax_t value, bool negative,
               const struct integer_base *b,
               const struct printf_conversion *c,
               void (*output) (char, void *), void *aux)
{
/* ... */

  // [BUG 1: hard-to-spot bug in conversion
  //  of large ints into comma-separated form.]
  cp = buf;
  group_cnt = 0;
  while (value > 0) {
    if((c->flags & GROUP)
       && group_cnt++ == b->group) {
      *cp++ = ',';
      group_cnt = 0;
    }
    *cp++ = b->digits[value % b->base];
    value /= b->base;
  }
/* ... */

  // [BUG 2: appending sign always, should
  //  only do if format specifier is signed!]
  if (c->flags & PLUS)
    *cp++ = negative ? '-' : '+';
  else if (c->flags & SPACE)
    *cp++ = negative ? '-' : ' ';
  else if (negative)
    *cp++ = '-';
/* ... */

```

Figure 6: Pintos’ format_integer routine: contains two, difficult to find errors immediately detected using EGT.

Format Length	Pintos’ printf	Embedded printf	GCCfast printf
2	34 21s	17 2s	30 15s
3	356 4m0s	75 1m48s	273 3m10s
4	3234 40m47s	337 21m6s	2105 87m36s
128	590 123m56s	72 119m38s	908 120m19s

Table 2: Test suites generated for printf, the first row of each size gives the number of generated tests, the second row the time required to do so.

	Pintos’ printf	Embedded printf	GCCfast printf
Mismatches self tests	426 of 4214	146 of 501	7 of 3316
Mismatches all tests	624 of 8031	6395 of 8031	91 of 8031
Statement Coverage	95% (172 lines)	95% (101 lines)	98% (63 lines)

Table 3: Mismatches found in the printf implementations.

was surprising since it only does minimal parsing and then just calls fprintf, which then calls glibc’s printf). Since we had access to the implementor of Pintos we focused on these; we discuss these below.

Second, we took the tests generated by all implementations and cross-checked their output against each other. Since they intentionally implement different subsets of the standard, we expect them to have different behavior. This experiment tests whether EGT can find such differences automatically. It can: 624 in Pintos, 6395 in Embedded and 91 in GCCfast.

Note that in both experiments, the Pintos and the GCCfast printf routines print an error message and abort when they receive a format string that they cannot handle. Since they only intend to handle a subset of the standard, this is correct behavior, and we do not report a mismatch in this case. In contrast, the Embedded printf instead fails silently when it receives a format string which it cannot handle. This means that we cannot differentiate between an incorrect output of a handled case and an unhandled case, and thus we report all these cases as mismatches.

Table 3 also shows the statement coverage achieved by these test suites; all printf’s achieve more than 95% coverage. Most of the lines that were not cov-

ered are unreachable. For example, Pintos' `printf` has a `NOT_REACHED` statement which should never be reached as long as Pintos treats all possible format strings. Similarly, for the Embedded `printf`, we don't reach the lines which redirect the output to a string buffer instead of `stdout`; these lines are used by `sprintf`, and never by `printf`. Some lines however were not reached because our system treats only the format string as symbolic, while the rest of the arguments are concrete. Finally, two of the three `printf` implementations use non-standard implementations for determining whether a character is a digit, which our system does currently not handle correctly. The number of lines reported in Table 3 are real lines of code, that is lines which have at least one instruction.

We reported all mismatches from Pintos to its developer, Ben Pfaff. We got confirmation and fixes of the following bugs.

Incorrect grouping of integers into groups of thousands.

“Dammit. I thought I fixed that... Its quite obviously incorrect in that case.” — Ben Pfaff, unsolicited exclamation, 3/23/05, 3:11pm.

The code mishandled the “,” specifier that says to comma-separate integer digits into groups of three. The exact test case was:

```
// correct: -155,209,728
// pintos : -15,5209,728
printf("%' d", -155209728);
```

Amusingly enough, the bug had been fixed in the developer's tree, but he had forgotten to push this out to the released version (which we were testing).

Incorrect handling of the space and plus flags.

“That case is so obscure I never would have thought of it.” — Ben Pfaff, unsolicited exclamation, 3/23/05, 3:09pm.

The character “%” can be followed by a space flag, which means that “a blank should be left before a positive number (or empty string) produced by a signed conversion” (man `printf(3)`). Pinto incorrectly leaves a blank before an unsigned conversion too. We found a similar bug for the plus flag.

This bug and the previous error both occurred in the same routine, `format_integer`, which deals with formating integers. The routine is shown in Figure ???. The complexity of the specification of even this one small helper function is representative of the minutia-laden constraints placed on many systems interfaces and their internals. The bugs are labeled BUG 1 and BUG 2 respectively. The only thing clear from their associated code fragments is that the cause of each error is not clear at all.

We now give a more cursory description of the remaining errors.

Incorrect alignment of strings. Pintos incorrectly handles width fields with strings, although this feature works correctly for integers (which got better testing).

Incorrect handling of the t and z flags. When the flag `t` is used, the unsigned type corresponding to `ptrdiff_t` should be used. This is a detail of the standard which was overseen by the developer. We found a similar bug for the `z` flag, which specifies that the signed type corresponding to `size_t` should be used.

No support for wide strings and chars. Pintos does not support wide string and wide chars, but fails silently in this case with no error message.

Undefined behavior. We found several bugs which are caused by underspecified features. An example of such a case is `printf(`%hi', v)`, whose output is undefined if `v` cannot be represented as a `short`.

6 Case study: WsMp3

This section applies our technique to the WsMp3 web server designed for transferring MP3 files [28]. We use WsMp3 version 0.0.5 which, uninstrumented contains about 2,000 lines of C code; instrumented about 40,000. This version contains a security vulnerability that allows attackers to execute arbitrary commands on the host machine [26, 27]. Our technique automatically generated test cases that found this security hole. In addition, it found three other memory overflows and an infinite loop caused by bad network input (which could be used for a DoS attack).

We first discuss how we set up test generation, coverage results, and then the most direct method of effectiveness: bugs found.

6.1 Setting up WsMp3

WsMp3 has the typical web server core: a main loop that listens for connections using `accept`, reads packet from the connection using `recv`, and then does operations based on the packet value. It also has a reasonably rich interaction with the operating system. As a first cut we only made the network packet's returned by `recv` be symbolic, but made the packet size be concrete. We did so by replacing calls to `recv` with calls to a model of it (`recv_model`) that just “returned” a symbolic array of bytes of a specific length. Figure 7 gives this code. It “reads in” a message of length `msg_len` by telling the system the address range between `buf` and `buf+msg_len` should be treated as symbolic. We then generated test cases for one byte packet, two bytes, and so forth by changing `msg_len` to the desired length.

```

// [model does not generate failures; msg_len is fixed]
ssize_t recv_model(int s, char *buf, size_t len, int flags) {
    make_bytes_symbolic(buf, msg_len);
    return msg_len;
}

```

Figure 7: Model for the `recv` system call to symbolically “receive” a packet of (fixed) size `msg_len`.

After the webserver finishes processing a message, we inserted a call into the system to emit concrete values associated with the message’s constraints. We then emit these into a test file and run it on it.

One subtlety is that after the webserver processes a single message we exit it. Recall that at every conditional on a symbolic value (roughly) we fork execution. Thus, the webserver will actually create many different children, one for each branch point. Thus, even processing a “single” message will generate many many test messages. In the context of this server, one message has little to do explicitly with another and thus we would not get any more test cases by doing additional ones. However, for a more stateful server, we could of course do more than one.

Finally, it was not entirely unheard of for even the symbolic input to cause the code to crash during test generation. We handle segmentation faults by installing a handler for the `SIGSEGV` signal and, if it is invoked, generate a concrete test case for the current constraints and then exit the process.

Since `WsMp3` makes intensive use of the standard string library, we used our own `string.h` library described in Section 3.4. In our tests, using this library improves performance by roughly seven-fold.

6.2 Test generation measurements

Packet Size	Unfinished Queries	Execution Time (s)	Test Suite Size
1	0	0s	1
2	0	0s	1
3	0	57s	18
4	0	10m28s	90
5	8	16m13s	97
12	134	14h15m	1173
128	63	14h15m	165

Table 4: Test suites generated for `WsMp3`. We stopped test generation for size 12 and 128 after roughly 14 hours.

We used EGT testing to generate tests for packets of size 1, 2, 3, 4, 5, 12, and 128. Table 4 gives (1) the

number of tests generated for each size, (2) the time it took (user time), and (3) the number of times the CVCL constraint solver failed to generate a concrete test from a set of constraints within 30 seconds.

Given our naive implementation, the test generation time was non-trivial. For packets of size 12 and 128 we stopped it after 14 hours (they were running on a laptop that we wanted to write this paper on). However, note that in some sense high test generation cost is actually not so important. First, test generation happens infrequently. The frequent case, running the generated tests, takes less than a minute (while to test all the random tests generated it takes about two hours and half). Second, test generation is automatic. The time to manually generate tests that would get similar amounts types of path coverage would be enormous. Further, manual generation easily misses cases silently. Finally, as far as we know, there was no test suite for `WsMp3`. Clearly the EGT alternative is much better.

Packet Size	10 tests	1000 tests	100,000 tests	EGT Testing
1	13.3%	13.3%	13.3%	13.3%
2	13.3%	13.3%	13.3%	13.3%
3	23.0%	23.1%	23.1%	23.1%
4	23.1%	23.1%	23.1%	28.1%
5	23.1%	23.1%	23.1%	29.6%
128	23.1%	23.1%	23.4%	31.2%
256	23.1%	23.1%	23.3%	
512	23.1%	23.1%	23.4%	
Total Time	11s	143s	2h24m	52s

Table 5: Statement coverage of EGT versus random testing. Random testing quickly reaches its asymptotic limit.

We compare coverage from EGT to random testing. We use state statement coverage generated using `gcc` and `gcov`. We would have preferred a more insightful metric than line coverage, but were not able to find adequate tools. We generated random tests by modifying `recv_model` routine to request messages filled with random data of a given size. For each packet size, we generate 10, 1000, and 100,000 random tests. Table 5 presents the time it takes to do a given number of random tests and statement coverage achieved by it and EGT.

The statement coverage reported for random testing is cumulative: each data point reports the statement coverage achieved by all the test cases of that message size and smaller.

EGT hits roughly 9% more lines of code than random; this is almost certainly a dramatic underreporting of the number of distinct paths it hits. More importantly, these lines appear out of reach of random testing no matter how

many more random tests we do.

We manually examined the code to see why EGT missed the other statements. We discuss the reasons below:

1. **Debugging and logging code:** we did not enable either debugging or logging code, which respectively account for roughly 5% and 10% of code statements.
2. **Error messages:** WsMp3 tests whether various resource allocation functions fail, and if so, it terminates with an error message. Most of the code in this category checks the return statement value from `malloc`. These checks account for approximately 3% of the code.
3. **Arguments to main:** The code which processes the command-line arguments accounts for approximately 4% of the code. We are currently not treating command-line arguments as symbolic inputs.

However, the rest of approximately 45% of the code is not reached because the request messages that we fabricate do not refer to valid files on the disk, or because we fail to capture several timing constraints.

As an example from the first category, when a GET request is received, the web server extracts the file name from the request packet, and then it checks if the file exists by using `fopen`. If the file does not exist, WsMp3 sends a corresponding error message to the client. If the file is valid, the file name is passed through various procedures for further processing. Since we don't have any files on our server, and since almost all the files being fabricated by our system would be invalid anyway, the code which process files and file names is never invoked.

The right way to solve this problem is to provide models for functions such as `fopen`, `fread`, and `stat`. However, even without these models, we find interesting errors, as the next subsection describes.

6.3 Errors Found

We have identified five errors in the code which parses the request messages received by WsMp3. All were caused by a series of incorrect assumptions that WsMp3 makes about the request being processed. We describe three illustrative bugs below.

Figure 8 gives the first bug. Here WsMp3 assumes that the first part of the request message (held in `buf`) holds the type of the client request, such as GET or POST, separated from the rest of the message by a space. After a request is received, WsMp3 copies this action type in an auxiliary buffer by copying all the characters from the original request, until a space is encountered. Unfortunately, it assumes the request is legal rather than potentially malicious and allocates only ten bytes for this

```

// [buf holds network message]
char* get_op(char *buf) {
    char* op;
    int i;

    if((op=(char *)malloc(10))==NULL) {
        printf("Not enough memory! \n");
        exit(1);
    }
    // [note: buf is '0' terminated]
    if(buf!=NULL && strlen(buf)>=3) {
        //strncpy(op,buf,3);
        i=0;
        while(buf[i]!=' ') {
            op[i]=buf[i];
            i++;
        }
        op[i]='\0';
    }
    else op=NULL;

    return op;
}

```

Figure 8: WsMp3 buffer overflow bug: occurs if received message (held in `buf`) has more than 10 characters before the first space.

buffer. Thus, if it receives an invalid request which does not contain a space in the first ten characters, than buffer overflows and WsMp3 usually terminates with a segmentation fault. Amusingly, there is a (commented out) attempt to instead do some sort of copy using the safe `strncpy` routine which will only up to a pre-specified length.

This routine is involved in a second bug. As part of the checking it does do, it will return `NULL` if the input is `NULL` or if the size of the incoming message is less than three characters. However, the caller of this routine does not check for a `NULL` return and always passes the buffer to `strcmp`, causing a remote-triggered segmentation fault.

The third final bug was interesting: for certain rare request messages (where the sixth character is either a period or a slash, and is followed by zero or more periods or slashes, which are immediately followed by a zero), WsMp3 goes into an infinite loop. Our EGT system automatically generates the very unusual message required to hit this bug. Figure 9 gives the problematic code.

7 Related Work

We compare EGT to past test generation work and then to bug finding methods.

```

while (cp[0] == '.' || cp[0] == '/')
  for (i=1; cp[i] != '\0'; i++) {
    cp[i-1] = cp[i];
    if (cp[i+1] == '\0')
      cp[i] = '\0';
}

```

Figure 9: The WsMp3 infinite loop error. `cp` points to the sixth character in the message buffer.

7.1 Test and input generation

To the best of our knowledge, while there has been work related to test generation and synthesis of program inputs to reach a given program point, there is no approach that effectively generates comprehensive tests automatically from a real program. There certainly exists no tool that can handle systems code. We first compare to static and then dynamic techniques below.

Static techniques. There has been a long stream of research that attempts to use static techniques to generate inputs that will cause execution to reach a specific program point or path.

One of the first papers to attack this problem, Boyer et al. [6], proposes the use of symbolic execution to follow a given path was in the context of a system, SELECT, intended to assist in debugging programs written in a subset of LISP. The usage model was that the programmer would *manually* mark each decision point in the path that they wanted executed and the system would incrementally attempt to satisfy each predicate.

More recently, researchers have tended to use static analysis to extract constraints which they then use various methods to try to solve.

One example is Gotlieb et al [17], who statically extracted constraints which they tried to solve using (naturally) a constraint solver. More recently, Ball [1] statically extracted predicates (i.e., constraints) using “predicate abstraction” [2] and then used a model checker to try to solve these predicates for concrete values.

There are many other similar static efforts. In general, static techniques are vastly weaker than dynamic at gathering the type of information needed to generate real test cases. They can deal with limited amounts of fairly straightforward code that does not interact much (or at all) with the heap or complex expressions, but run into intractable problems fairly promptly.

Dynamic techniques. Much of the test generation work relies on the use of a non-trivial manually-written specification of some kind. This specification is used to guide the generation of testing values ignoring the details of a given implementation. One of the most interesting examples of such an approach is Korat [5], which takes a specification of a data-structure (such as a linked

list or binary tree) and exhaustively generates all non-isomorphic data structures up to a given size, with the intention of testing a program using them. They use several optimizations to prune data structure possibilities, such as ignoring any data structure field not read by a program. EGT differs from this work by attempting to avoid any manual specification and targeting a much broader class of tested code.

Past automatic input generation techniques appear to focus primarily on generating an input that will reach a given path, typically motivated by the (somewhat contrived) problem of answering programmer queries as to whether control can reach a statement or not.

Ferguson and Korel[14] iteratively generate test cases with the goal of hitting a specified statement. They start with an initial random guess, and then iteratively refine the guess to discover a path likely to hit the desired statement.

Gupta et al. [18] use a combination of static analysis and generated test cases to hit a specified path. They define a loss function consisting of “predicate residuals” which roughly measures by “how much” the branch conditions for that path were not satisfied. By generating a series of test cases, they use a numerical solver to find test case values that can trigger the given path. Gupta’s technique combines some symbolic reasoning with dynamic execution, mitigating some of the problems inherit in either approach but not in both. Unfortunately, the scalability of the technique has more recently been called into question, where small systems can require the method to take an unbounded amount of time to generate a test case [12].

In EGT differs from this work by focusing on the problem of comprehensively generating tests on all paths controlled by input. This prior work appears to be much more limited in this regard.

7.2 Bug finding

Software Model Checking. Model checkers have been previously used to find errors in both the design and the implementation of software systems [19, 16, 20, 7, 9, 3, 16]. These approaches tend to require significant manual effort to build testing harnesses. However, to some degree the approaches are complementary: the tests our approach generates could be used to drive the model checked code.

Generic bug finding. There has been much recent work on bug finding [11, 3, 10, 8]. Roughly speaking [13], because static analysis can examine all paths and only needs to compile code in order to check it, it is relatively better at finding errors in surface properties visible in the source (“lock is paired with unlock”) than dynamic techniques. In contrast, because dynamic

checking runs code it is limited to just executed paths, but can more effectively check deeper properties implied by code. For example that the code will infinite loop on bad inputs, that a formatting command is not obeyed correctly. Many of the errors in this paper would be difficult to get with that approach. However, we view static analysis as complementary to EGT testing — it is lightweight enough that there is no reason not to apply it and then use EGT.

8 Conclusion

This paper has proposed a simple method of automatically generating test cases by executing code on symbolic inputs called execution generated testing. We build a prototype EGT system and applied it to real code. We found numerous corner-case errors ranging from simple memory overflows and infinite loops to subtle issues in the interpretation of language standards.

These results, and our experience dealing with and building systems suggests that EGT will work well on systems code, with its often complex requirements and tangled logic.

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